

Spiral plat avec une seule courbe terminale externe

Influence d'une déformation de la courbe terminale

Calculs numériques et approximations de Haag

Caractéristiques du spiral

➔ Référence : C:\Résonateur (TA)\Data\Bal_spiral plat (ex num).mcd(R)

➔ Référence : C:\Résonateur (TA)\Data\Définition Atan.mcd(R)

Dimensions $\acute{e}p = 0.03 \text{ mm}$ $ha = 0.15 \text{ mm}$ $S = 4.5 \times 10^{-3} \text{ mm}^2$ $TOL := 10^{-12}$

$d_{2sp} = 4.52 \text{ mm}$ $d_V := 1.1 \cdot \text{mm}$ $d_B := d_{1sp}$ $\rho_{sp} = 0.135 \text{ mm}$ $n_{sp} := \frac{d_{2sp} - d_B}{2 \cdot \rho_{sp}}$

$L := \pi \cdot \frac{n_{sp}}{2} \cdot (d_{2sp} + d_B)$ $L = 11.182 \text{ cm}$ $\psi_0 := 2 \cdot \pi \cdot n_{sp}$ $\psi_0 = 4.56 \times 10^3 \text{ deg}$

Position du point de raccordement sur le spiral $\alpha_A := \pi$ $r_A := 0.5 \cdot d_{2sp}$ $z_A := r_A \cdot e^{i \cdot \alpha_A}$

Forme initiale du spiral

$a := \frac{\rho_{sp}}{2 \cdot \pi}$ $r_s(\alpha) := r_A - a \cdot (\alpha - \alpha_A)$ $x_{0s}(\alpha) := r_s(\alpha) \cdot \cos(\alpha)$ $y_{0s}(\alpha) := r_s(\alpha) \cdot \sin(\alpha)$

$s(\alpha) := \frac{1}{2 \cdot a} \cdot (r_A^2 - r_s(\alpha)^2)$ $s(\alpha) := r_A \cdot (\alpha - \alpha_A) - \frac{a}{2} \cdot (\alpha - \alpha_A)^2$

➔ Référence : C:\Résonateur (TA)\Tables\Modules J, I et W des barres élastiques.mcd(R)

$l_{33} := l_{f_rect}(\acute{e}p, ha)$

Courbe terminale externe

$r_{t1} := 0.8$ $r_{Ph} := \text{racine} \left[(2 \cdot r_{t1} - 1)^4 - 4 \cdot (1 - r_{t1})^4 - \pi^2 \cdot r_{t1}^2 \cdot (1 - r_{t1})^2, r_{t1} \right] \cdot r_A$ $r_{Ph} = 0.832 r_A$

$r_{t2}(r_{t1}) := 2 \cdot r_{t1} - r_A$ $\beta_0 := \arctan \left[\frac{\pi \cdot r_{Ph}}{2 \cdot (r_A - r_{Ph})} \right]$ $\beta_0 = 82.695 \text{ deg}$ $l_t(r_{t1}) := r_{t2}(r_{t1}) \cdot \beta_0 + \pi \cdot r_{t1}$

$X_{0t1}(r_{t1}, \alpha_t) := r_A - r_{t1} + r_{t1} \cdot \cos(\alpha_t)$ $Y_{0t1}(r_{t1}, \alpha_t) := r_{t1} \cdot \sin(\alpha_t)$

$X_{0t2}(r_{t1}, \beta_t) := -r_{t2}(r_{t1}) \cdot \cos(\beta_t)$ $Y_{0t2}(r_{t1}, \beta_t) := -r_{t2}(r_{t1}) \cdot \sin(\beta_t)$ $OA := r_A \cdot e^{i \cdot \pi}$

Position du point d'attache

$\alpha_B := \text{mod}(\psi_0 + \pi, 2 \cdot \pi)$ $\alpha_B = 60 \text{ deg}$ $r_B := 0.5 \cdot d_B$

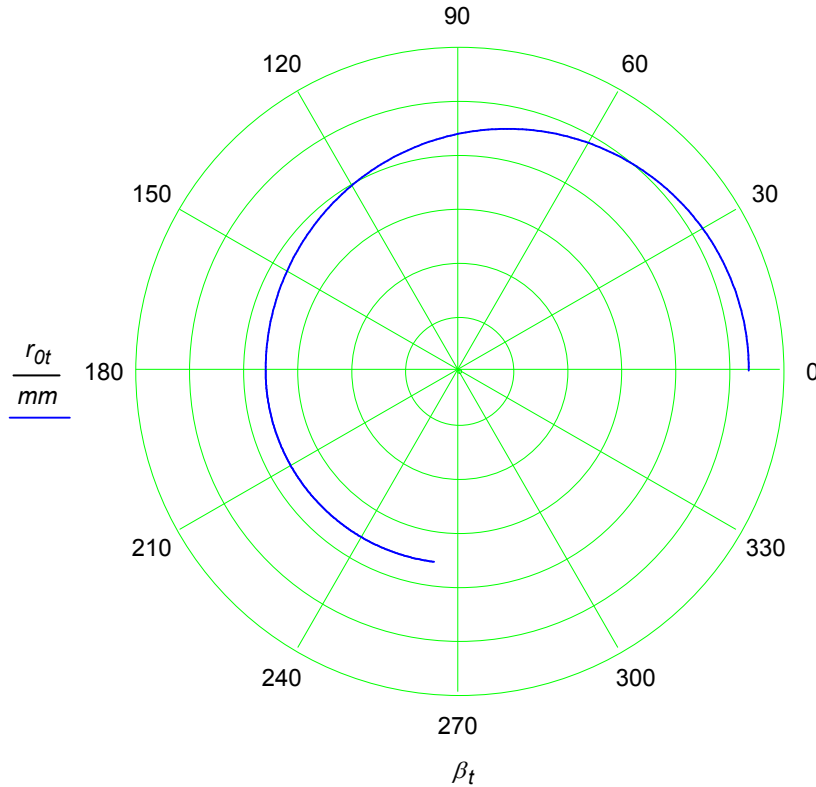
$OB := r_B \cdot e^{i \cdot (\pi + \psi_0)}$ $L_t(r_{t1}) := l_t(r_{t1}) + L$

Graphe

$n_t := 201$ $j := 0..n_t - 1$ $\Delta\alpha_t := \frac{\pi}{n_t - 1}$ $\alpha_{t_j} := j \cdot \Delta\alpha_t$ $X_{t_j} := X_{0t1}(r_{Ph}, \alpha_{t_j})$ $Y_{t_j} := Y_{0t1}(r_{Ph}, \alpha_{t_j})$

$\Delta\beta_t := \frac{\beta_0}{n_t - 1}$ $\beta_{t_j} := j \cdot \Delta\beta_t$ $X_{t2_j} := X_{0t2}(r_{Ph}, \beta_{t_j})$ $Y_{t2_j} := Y_{0t2}(r_{Ph}, \beta_{t_j})$

$X_t := \text{pile}(X_t, X_{t2})$ $Y_t := \text{pile}(Y_t, Y_{t2})$ $r_{Ot} := \sqrt{X_t^2 + Y_t^2}$ $\beta_t := \text{Atan}(X_t, Y_t)$



Perturbation de période en position horizontale

Cas d'une courbe de Phillips

Paramètres de la courbe terminale externe

$$Z_{0t1}(r_{t1}, \alpha) := X_{0t1}(r_{t1}, \alpha) + i \cdot Y_{0t1}(r_{t1}, \alpha) \quad Z_{0t2}(r_{t1}, \alpha) := X_{0t2}(r_{t1}, \alpha) + i \cdot Y_{0t2}(r_{t1}, \alpha)$$

$$Z_1(r_{t1}) := \frac{1}{2} \cdot \left(\int_0^\pi Z_{0t1}(r_{t1}, \alpha) \cdot r_{t1} d\alpha + \int_0^{\beta_0} Z_{0t2}(r_{t1}, \beta) \cdot r_{t2}(r_{t1}) d\beta \right) - i$$

$$\rho_{01} := |Z_1(r_{Ph})| \quad \varphi_{01} := \arg(Z_1(r_{Ph})) \quad \boxed{\rho_{01} = 0} \quad \boxed{\varphi_{01} = -90 \text{ deg}}$$

$$Z_2(r_{t1}) := \frac{1}{3} \cdot \left[\int_0^\pi r_{t1} \cdot \alpha \cdot Z_{0t1}(r_{t1}, \alpha) \cdot r_{t1} d\alpha + \int_0^{\beta_0} (r_{t1} \cdot \pi + r_{t2}(r_{t1}) \cdot \beta) \cdot Z_{0t2}(r_{t1}, \beta) \cdot r_{t2}(r_{t1}) d\beta \right] + 1$$

$$\rho_{02} := |Z_2(r_{Ph})| \quad \varphi_{02} := \arg(Z_2(r_{Ph})) \quad \boxed{\rho_{02} = 1.055} \quad \boxed{\varphi_{02} = 147.579 \text{ deg}}$$

Modifications de la forme de la courbe terminale

Valeurs de test

$$x_1 := 1.02 \quad x_2 := 0.98 \quad r_{t1} := x_1 \cdot r_{Ph}$$

$$\rho_1(r_{t1}) := |Z_1(r_{t1})| \quad \varphi_1(r_{t1}) := \arg(Z_1(r_{t1})) \quad \rho_2(r_{t1}) := |Z_2(r_{t1})| \quad \varphi_2(r_{t1}) := \arg(Z_2(r_{t1}))$$

$$\boxed{\rho_1(r_{t1}) = 0.082} \quad \boxed{\varphi_1(r_{t1}) = 168.521 \text{ deg}} \quad \boxed{\rho_2(r_{t1}) = 1.274} \quad \boxed{\varphi_2(r_{t1}) = 156.245 \text{ deg}}$$

Calcul numérique de la perturbation de période

$$w_A(r_{t1}, \theta) := \left[i \cdot \left(r_A \cdot \rho_1(r_{t1}) \cdot e^{-i \cdot \varphi_1(r_{t1})} + 2 \cdot a \right) + \frac{\theta}{L_t(r_{t1})} \cdot r_A^2 \cdot \rho_2(r_{t1}) \cdot e^{-i \cdot \varphi_2(r_{t1})} \right] \cdot \exp \left(i \cdot \theta \cdot \frac{l_t(r_{t1})}{L_t(r_{t1})} \right) \cdot \mathbf{OA}$$

$$w_B(r_{t1}, \theta) := \left[-i \cdot \left(i \cdot r_B + 2 \cdot a \right) - \frac{\theta}{L_t(r_{t1})} \cdot r_B^2 \right] \cdot \exp \left(i \cdot \theta \cdot \frac{l_t(r_{t1}) + L}{L_t(r_{t1})} \right) \cdot \mathbf{OB}$$

$$w(r_{t1}, \theta) := \frac{\theta}{L_t(r_{t1})} \cdot (w_A(r_{t1}, \theta) + w_B(r_{t1}, \theta)) \quad w(r_{t1}, \theta_0) = 0.019 + 0.019i \text{ mm}$$

$$\sigma_2 := \frac{r_A^2 + r_B^2}{2} \quad \sigma_2 = 2.705 \text{ mm}^2 \quad X_w(r_{t1}, \theta) := \frac{(|w(r_{t1}, \theta)|)^2}{\sigma_2} \quad \gamma_w(r_{t1}, \theta) := \frac{d}{d\theta} X_w(r_{t1}, \theta)$$

$$\delta_H(r_{t1}, \theta_0) := \frac{-1}{2 \cdot \pi \cdot \theta_0} \cdot \int_0^{2 \cdot \pi} \gamma_w(r_{t1}, \theta_0 \cdot \cos(\varphi)) \cdot \cos(\varphi) d\varphi$$

$$\mu_H(x, \theta_0) := -86400 \cdot \delta_H(x \cdot r_{Ph}, \theta_0)$$

$$\mu_H(x_1, \theta_0) = 2.401$$

$$\mu_H(x_1, 180 \cdot \text{deg}) = 0.655$$

Solution analytique

$$A(r_{t1}) := \frac{1}{L_t(r_{t1})^2} \cdot \left[r_A^4 \cdot \rho_1(r_{t1})^2 + r_B^4 + 4 \cdot a \cdot r_A^3 \cdot \rho_1(r_{t1}) \cdot \cos(\varphi_1(r_{t1})) + 4 \cdot a^2 \cdot (r_A^2 + r_B^2) \right]$$

$$B(r_{t1}) := \frac{3}{2 \cdot L_t(r_{t1})^4} \cdot (r_A^6 \cdot \rho_2(r_{t1})^2 + r_B^6)$$

$$C1(r_{t1}) := 2 \cdot a \cdot r_A \cdot r_B \cdot (r_B \cdot \sin(\psi_0) - r_A \cdot \rho_1(r_{t1}) \cdot \cos(\psi_0 + \varphi_1(r_{t1})) - 2 \cdot a \cdot \cos(\psi_0))$$

$$C(r_{t1}) := \frac{2}{L_t(r_{t1})^2} \cdot (C1(r_{t1}) + r_A^2 \cdot r_B^2 \cdot \rho_1(r_{t1}) \cdot \sin(\psi_0 + \varphi_1(r_{t1})))$$

$$D1(r_{t1}) := r_A^2 \cdot r_B^2 \cdot \rho_1(r_{t1}) \cdot \cos(\psi_0 + \varphi_1(r_{t1})) + r_A^2 \cdot r_B \cdot \rho_2(r_{t1}) \cdot \sin(\psi_0 + \varphi_2(r_{t1}))$$

$$D(r_{t1}) := \frac{2 \cdot r_A \cdot r_B}{L_t(r_{t1})^3} \cdot \left[D1(r_{t1}) + 2 \cdot a \cdot (r_B^2 \cdot \cos(\psi_0) - r_A^2 \cdot \rho_2(r_{t1}) \cdot \cos(\psi_0 + \varphi_2(r_{t1}))) \right]$$

$$K(r_{t1}) := \frac{2}{L_t(r_{t1})^4} \cdot r_A^3 \cdot r_B^3 \cdot \rho_2(r_{t1}) \cdot \cos(\psi_0 + \varphi_2(r_{t1}))$$

$$F(x) := J0(x) - x \cdot J1(x) \quad H(x) := x \cdot (1 + x^2) \cdot J1(x) - 2 \cdot x^2 \cdot J0(x) \quad G(x) := -x \cdot (J1(x) + x \cdot J0(x))$$

$$\delta_{aH}(r_{t1}, \theta_0) := \frac{-1}{\sigma_2} \cdot (A(r_{t1}) + B(r_{t1}) \cdot \theta_0^2 + C(r_{t1}) \cdot F(\theta_0) + D(r_{t1}) \cdot G(\theta_0) + K(r_{t1}) \cdot H(\theta_0))$$

$$\mu_{aH}(x, \theta_0) := -86400 \cdot \delta_{aH}(x \cdot r_{Ph}, \theta_0)$$

$$\mu_{aH}(x_1, \theta_0) = 2.472$$

$$\mu_{aH}(x_1, 180 \cdot \text{deg}) = 0.784$$

Courbes Phillips

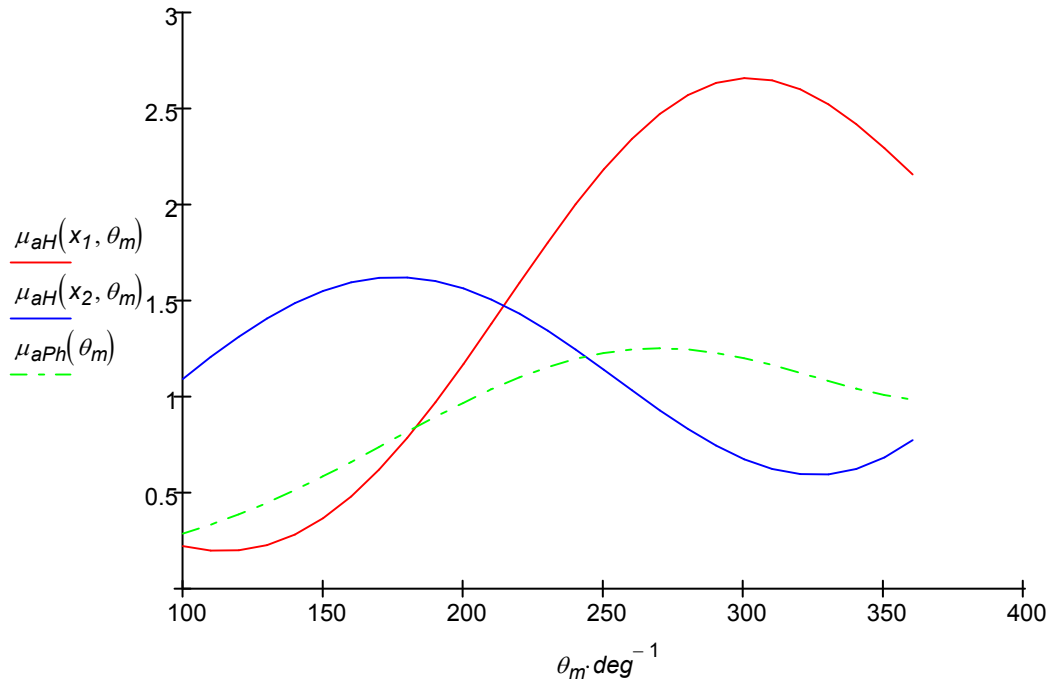
$$\mu_{aPh}(\theta_0) := -86400 \cdot \delta_{aH}(r_{Ph}, \theta_0)$$

$$\mu_{aPh}(\theta_0) = 1.251$$

$$\mu_{aPh}(180 \cdot \text{deg}) = 0.816$$

$$\theta_m := 100 \cdot \text{deg}, 110 \cdot \text{deg} .. 360 \cdot \text{deg}$$

$$x_1 := 1.02 \quad x_2 := 0.98$$



Déplacement du centre de gravité

Modifications de la forme des courbes terminales

$$\kappa := 0.367$$

$$f_g(r_{t1}, \theta, s) := \left[1 + i \cdot \theta \cdot \left(\frac{s}{L_t(r_{t1})} - \kappa \right) \right] \cdot e^{i \cdot \theta \cdot \frac{s}{L_t(r_{t1})}} \quad f_{g1}(r_{t1}, \theta, s) := \frac{d}{ds} f_g(r_{t1}, \theta, s)$$

$$f_{gA}(r_{t1}, \theta) := f_g(r_{t1}, \theta, l_t(r_{t1})) \quad f_{gB}(r_{t1}, \theta) := f_g(r_{t1}, \theta, l_t(r_{t1}) + L)$$

$$f_{g1A}(r_{t1}, \theta) := f_{g1}(r_{t1}, \theta, l_t(r_{t1})) \quad f_{g1B}(r_{t1}, \theta) := f_{g1}(r_{t1}, \theta, l_t(r_{t1}) + L)$$

$$\zeta_{at}(r_{t1}, \theta) := \left[\left(r_A \cdot \rho_1(r_{t1}) \cdot e^{-i \cdot \varphi_1(r_{t1})} + 2 \cdot a \right) \cdot f_{gA}(r_{t1}, \theta) - r_A^2 \cdot \rho_2(r_{t1}) \cdot e^{-i \cdot \varphi_2(r_{t1})} \cdot f_{g1A}(r_{t1}, \theta) \right] \cdot \mathbf{OA}$$

$$\zeta_{at}(r_{t1}, \theta) := \left[- (i \cdot r_B + 2 \cdot a) \cdot f_{gB}(r_{t1}, \theta) + r_B^2 \cdot f_{g1B}(r_{t1}, \theta) \right] \cdot \mathbf{OB}$$

$$\zeta_a(x, \theta) := \frac{1}{L_t(x \cdot r_{Ph})} \cdot (\zeta_{at}(x \cdot r_{Ph}, \theta) + \zeta_{at}(x \cdot r_{Ph}, \theta))$$

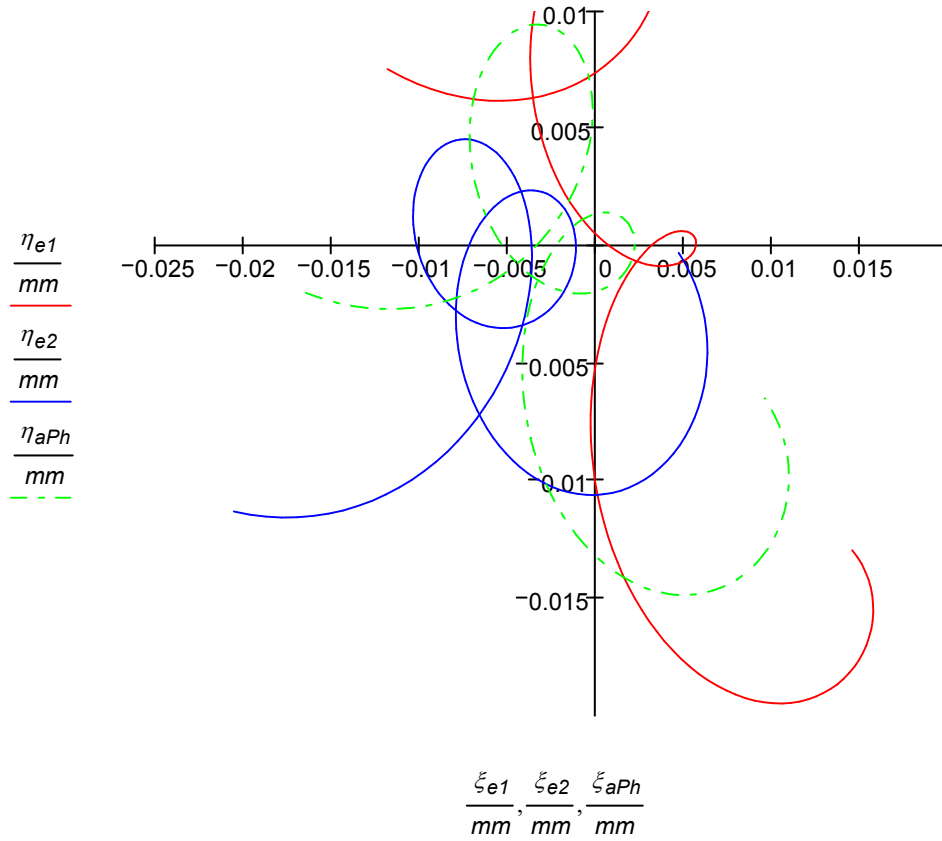
Courbes Phillips

$$\zeta_{aPh}(\theta) := \zeta_a(1, \theta)$$

Graphes du déplacement du centre de gravité

$$n := 201 \quad i := 0 .. n - 1 \quad \Delta\theta := \frac{4 \cdot \pi}{n - 1} \quad \theta_i := -2 \cdot \pi + i \cdot \Delta\theta \quad \xi_{aPh_i} := \text{Re}(\zeta_{aPh}(\theta_i)) \quad \eta_{aPh_i} := \text{Im}(\zeta_{aPh}(\theta_i))$$

$$\xi_{e1_i} := \text{Re}(\zeta_a(x_1, \theta_i)) \quad \eta_{e1_i} := \text{Im}(\zeta_a(x_1, \theta_i)) \quad \xi_{e2_i} := \text{Re}(\zeta_a(x_2, \theta_i)) \quad \eta_{e2_i} := \text{Im}(\zeta_a(x_2, \theta_i))$$



Perturbation de période en position verticale

Modifications de la forme des courbes terminales

$$f(r_{t1}, \theta_0, s) := \frac{s}{L_t(r_{t1})} \cdot \left[\left(\kappa - \frac{s}{L_t(r_{t1})} \right) \cdot J0 \left(\theta_0 \cdot \frac{s}{L_t(r_{t1})} \right) - \frac{1}{\theta_0} \cdot J1 \left(\theta_0 \cdot \frac{s}{L_t(r_{t1})} \right) \right]$$

$$f_1(r_{t1}, \theta_0, s) := \frac{d}{ds} f(r_{t1}, \theta_0, s)$$

$$f_A(r_{t1}, \theta_0) := f(r_{t1}, \theta_0, l_t(r_{t1})) \quad f_B(r_{t1}, \theta_0) := f(r_{t1}, \theta_0, l_t(r_{t1}) + L)$$

$$f_{1A}(r_{t1}, \theta_0) := f_1(r_{t1}, \theta_0, l_t(r_{t1})) \quad f_{1B}(r_{t1}, \theta_0) := f_1(r_{t1}, \theta_0, l_t(r_{t1}) + L)$$

$$Z_{a1}(r_{t1}, \theta_0) := \left[\left(r_A \cdot \rho_1(r_{t1}) \cdot e^{-i \cdot \varphi_1(r_{t1})} + 2 \cdot a \right) \cdot f_A(r_{t1}, \theta_0) - r_A^2 \cdot \rho_2(r_{t1}) \cdot e^{-i \cdot \varphi_2(r_{t1})} \cdot f_{1A}(r_{t1}, \theta_0) \right] \cdot \mathbf{OA}$$

$$Z_{a2}(r_{t1}, \theta_0) := \left[-i \cdot r_B + 2 \cdot a \right] \cdot f_B(r_{t1}, \theta_0) + r_B^2 \cdot f_{1B}(r_{t1}, \theta_0) \cdot \mathbf{OB}$$

$$Z_a(r_{t1}, \theta_0) := \frac{1}{L_t(r_{t1})} \cdot (Z_{a1}(r_{t1}, \theta_0) + Z_{a2}(r_{t1}, \theta_0))$$

$$\delta_{aV}(r_{t1}, \theta_0) := -g \cdot \frac{m_s \cdot L}{E \cdot I_{33}} \cdot \text{Im}(Z_a(r_{t1}, \theta_0))$$

$$\delta_{aV}(r_{t1}, \theta_0) = 2.284 \times 10^{-5}$$

$$\mu_{aV}(x, \theta_0) := -86400 \cdot \delta_{aV}(x \cdot r_{Ph}, \theta_0)$$

$$\mu_{aV}(x_1, \theta_0) = -1.974$$

$$\mu_{aV}(x_1, 180 \cdot \text{deg}) = -0.962$$

Courbes Phillips

$$\mu_{aVPh}(\theta) := \mu_{aV}(1, \theta)$$

$$\theta_m := 100 \cdot \text{deg}, 105 \cdot \text{deg} .. 360 \cdot \text{deg}$$

